

A-Level Physics Forced Vibrations and Resonance Mark Scheme

Time available: 78 minutes Marks available: 43 marks

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Mark schemes

- 1.
- (a) (mark should be at the equilibrium position) since this is where the mass moves with greatest speed [transit time is least] ✓

1

(b) (i) mean time for 20T (from sum of times $\div 5$) = 22.7 (s)₁ \checkmark (minimum 3sf)

uncertainty (from half of the range) = 0.3 (s) $_2$ \checkmark (accept trailing zeros here)

percentage uncertainty

(from
$$\frac{0.3}{22.7} \times 100$$
) $\left[\frac{100}{5} \times \sum \frac{0.3}{20T}\right] = 1.3 (22)\%_3$

(allow full credit for conversion from 20 T to T, e.g. 1.135 = $_1$ \checkmark 0.015 = $_2$ \checkmark ecf for incorrect $_1$ \checkmark and / or $_2$ \checkmark earns $_3$ \checkmark

3

(ii) natural frequency (from $\frac{20}{22.7}$ and minimum 2 sf) = 0.88 (1)Hz [accept s⁻¹] \checkmark

(ecf for wrong mean 20T; accept ≥ 4 sf)

1

(c) (i) linear scale with at least 3 evenly-spaced convenient values
 (i.e. not difficult multiples) marked; the intervals between 1 Hz marks must be 40 ± 2 mm (100 ± 5 mm corresponds to 2.5 Hz) ✓

(ecf for wrong natural frequency: 100 ± 5 mm corresponds to $\frac{2.5f}{0.88}$ Hz)

1

(ii) 4 mm [allow ± 0.2 mm] ✓

1

(d) (i) student decreased intervals [smaller gaps] between [increase frequency / density of] readings (around peak / where A is maximum) ✓ ✓

using data loggers with high sample rates)

[student took more / many / multiple readings (around peak)
✓]
(reject bland 'repeated readings' idea; ignore ideas about

2

(ii) new curve starting within ± 1 mm of A = 4 mm, f = 0 Hz with peak to right of that in Figure 3 (expect maximum amplitude shown to be less than for 2 spring system but don't penalise if this is not the case; likewise, the degree of damping need not be the same (can be sharper or less pronounced)
Peak at √2 value given in (b)(ii); expect 1.25 Hz so peak should be directly over 50 ± 5 mm but take account of wrongly-marked scale √

[11]

2

2.

(a) forced vibrations:

repeated upwards and downwards movement ✓
vibrations at frequency of support rod ✓
amplitude is small at high frequency or large at low frequency ✓
correct reference to phase difference between displacements
of driving and forced vibrations ✓

Acceptable references to phase differences:

Forced vibrations – when frequency of driver » frequency of driven, displacements are out of phase by (almost) π radians or 180° (**or** ½ a period) **or** when frequency of driver « frequency of driven, displacements are (almost) in phase. [Accept either]. [Condone >, < for », «].

resonance:

frequency of support rod **or** driver is equal to natural frequency

of (mass-spring) system √

large (or maximum) amplitude vibrations of mass ✓ maximum energy transfer (rate) (from support rod

to mass-spring system) ✓

correct reference to phase difference between displacements

of driving and driven vibrations at resonance \checkmark

Resonance – displacement of driver leads on displacement of driven by π / 2 radians or 90° **or** ¼ of a period (or driven lags on driver by π / 2 radians or 90° **or** ¼ of a period).

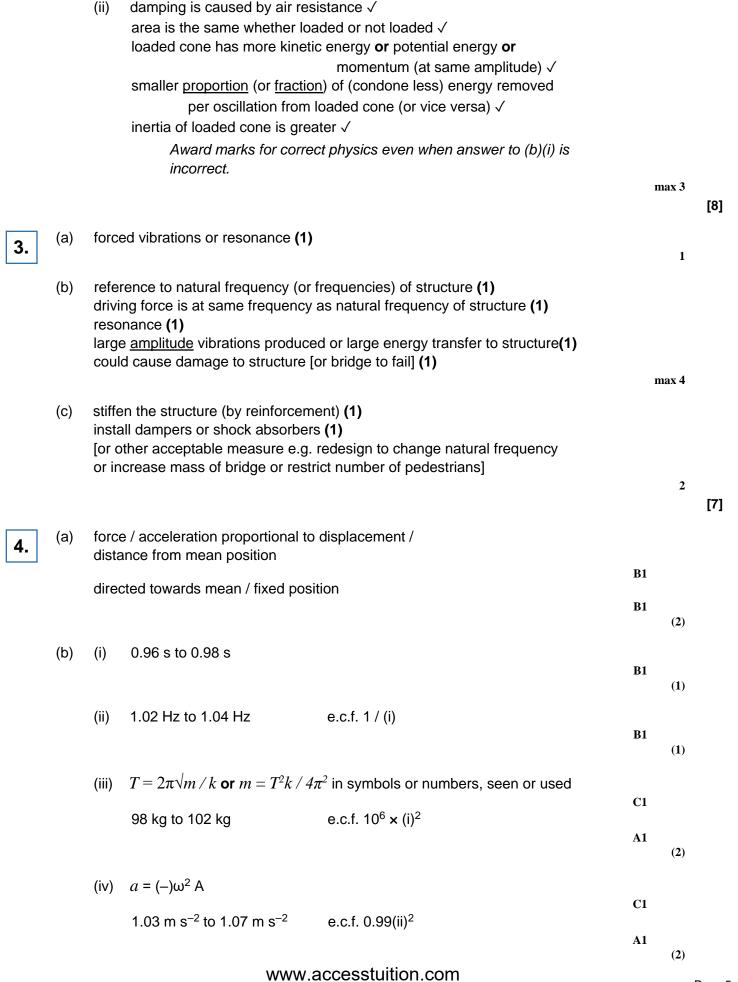
[Condone phase difference is π / 2 radians or 90°].

max 4

(b) (i) cone oscillates without ring (ticked)

Only one box to be ticked.

1



(c) time period (of oscillation caused by road markings) = s/v or 1.2 / 7 or 0.17 s **C1** frequency = 1 / T or 5.8 Hz(use of $v = f\lambda$ loses both of the 1st two marks) **A1** applied frequency / time period is different from natural / resonant frequency so no resonance **B1** (3) KE at P (d) (i) **B1** PE at Q **B1** at R, (nearly all of) energy absorbed by shock absorber / dissipated as internal energy (condone heat) in shock absorber / surroundings (allow lost in damping) **B1** (3) energy proportional to (amplitude)² (ii) **C1** at **P**, A = 2.5; at t, A = 1.0 or 0.9 **C1** 5.3 / 6.3 = 0.84 of energy absorbed at t (or 0.90, consistent with value of A at t) **A1 (3)** [17]