



A-Level Physics

Simple Harmonic Motion

Mark Scheme

Time available: 58 minutes

Marks available: 42 marks

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Mark schemes

1. (a) Use of time = angle / angular speed ✓
To get 3.5 s ✓ 2
- (b) Arrow towards centre of turntable starting at the block. ✓ 1
- (c) Use of $F = mr\omega^2$ ✓
To give 0.10 N ✓ 2
- (d) Block constantly changing direction (at constant speed) ✓
Ref to N1 and therefore force must apply ✓
OR
Changing direction shows (centripetal) acceleration ✓
Reference to N2 and therefore force must apply ✓ 2
- (e) Use of pendulum equation ✓
To give 1.55 m ✓ 2
- (f) Amplitude – the pendulum shadow amplitude becomes less than the block shadow amplitude ✓
Phase – time period decreases/changes as pendulum amplitude gets less/closer to zero so shadow of bob will move ahead of block/phase changes ✓
condone the two shadows remain in phase (as pendulum motion isochronous for small angles) 2

[11]

2.

- (a) (use of $v = 2\pi f\sqrt{a^2 - x^2}$)
 $v_{\max} = 2\pi \times 2.0 \times 2.5 \times 10^{-2}$
 $v_{\max} = 0.314 \text{ m s}^{-1} \checkmark$
(use of $E_k = \frac{1}{2}mv^2$)
 $54 \times 10^{-3} = \frac{1}{2}m \times (0.314)^2$
 $m = 1.1 \text{ (kg)} \checkmark$
 $f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$
 $2.0 \times 2\pi = \sqrt{(k/1.1)} \checkmark$
 $(k = (4\pi)^2 \times 1.1)$
 $k = 173 \text{ (172.8)} \checkmark (\text{N m}^{-1})$

Can

OR

$$5.4 \times 10^{-3} = \frac{1}{2} k (2.5 \times 10^{-2})^2 \checkmark$$
$$k = 173 \text{ (172.8)} \text{ N m}^{-1} \checkmark$$

If either of these methods used can then find mass from frequency formula or from kinetic energy

OR

$$54 \times 10^{-3} = \frac{1}{2} F \times 2.5 \times 10^{-2}$$
$$F = 4.32$$
$$4.32 = k \times 2.5 \times 10^{-2}$$
$$k = 173 \text{ (N m}^{-1}\text{)}$$

Accept 170 and 172.8 to 174

1
1
1
1

- (b) (use of $f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$)
same mass so $f \propto \sqrt{k}$
thus frequency = $2.0 \times \sqrt{3}$
frequency = 3.5 (3.46) (Hz) \checkmark

Allow CE from (a) for k or m

1
1

(c) Two from:

(resonance) peak / maximum amplitude is at a higher frequency ✓
due to higher spring constant ✓

(resonant) peak would be broader ✓
due to damping ✓

amplitude would be lower (at all frequencies) ✓
due to energy losses from the system ✓

First mark in each case for effect

Second mark for reason

2 marks max for effects

2 marks max for reason

Cannot award from sketch graph unless explained

First mark in each pair stand alone

Second mark conditional on first in each pair

1
1
1
1

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3.

(a) SHM is when

The acceleration is proportional to the displacement ✓

the acceleration is in opposite direction to displacement ✓

2

(b) $f = 1/T = 1/0.05 = 20 \text{ Hz}$ ✓

($v_{\max} = 2\pi fA$)

$$A = \frac{0.044}{2\pi \times 20} \checkmark (=3.5 \times 10^{-4} \text{ m})$$

2

(c) Cosine shape drawn, maximum at $t=0$, amplitude $3.5 \times 10^{-4} \text{ m}$ ✓

1

(d) (any of the following when the velocity is zero) 0.00s, 0.025s, 0.050s or 0.075s ✓

1

- (e) when the vibrating surface accelerates down with an acceleration less than the acceleration of free fall the sand stays in contact. ✓

above a particular frequency, the acceleration is greater than g ✓

there is no contact force on the sand **OR**

sand no longer in contact when downwards acceleration of plate is greater than acceleration of sand due to gravity ✓

3

- (f) (when the surface acceleration is the same as free fall)

$$g = r \omega^2 = A (2 \pi f)^2 \quad \checkmark$$

$$f = \sqrt{g / A 4 \pi^2} = (9.81 / (3.5 \times 10^{-4} \times 4 \pi^2))^{1/2} = 26.6(7) \text{ Hz} \quad \checkmark$$

2

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4.

- (a) acceleration is proportional to displacement (from equilibrium) ✓

Acceleration proportional to negative displacement is 1st mark only.

acceleration is in opposite direction to displacement

or towards a fixed point / equilibrium

Don't accept "restoring force" for accln.

position ✓

2

(b) (i) $f \left(= \frac{1}{2\pi} \sqrt{\frac{g}{l}} \right) = \frac{1}{2\pi} \sqrt{\frac{9.81}{0.984}} \quad \checkmark = 0.503 \text{ (0.5025) (Hz)} \quad \checkmark$

3SF is an independent mark.

[**or** $T \left(= 2\pi \sqrt{\frac{l}{g}} \right) = 2\pi \sqrt{\frac{0.984}{9.81}} \quad \checkmark (= 1.9(90) \text{ (s)})$

When $g = 9.81$ is used, allow either 0.502 or 0.503 for 2nd and 3rd marks.

$$f \left(= \frac{1}{T} \right) = \frac{1}{1.990} = 0.503 \text{ (0.5025) (Hz)} \quad \checkmark]$$

Use of $g = 9.8$ gives 0.502 Hz: award only 1 of first 2 marks if quoted as 0.502, 0.503 0.50 or 0.5 Hz.

answer to **3SF** ✓

3

$$(ii) \quad a(= -(2\pi f)^2 x) = (-)(2\pi \times 0.5025)^2 \times 42 \times 10^{-3} \quad \checkmark$$

Allow ECF from **any** incorrect f from (b)(i).

$$= 0.42 \text{ (0.419) (m s}^{-2}\text{)} \quad \checkmark$$

2

(c) recognition of 20 oscillations of (shorter) pendulum

and / or 19 oscillations of (longer) pendulum \checkmark

Explanation: difference of 1 oscillation or phase change of 2π

or $\Delta t = 0.1$ so $n = 2 / 0.1 = 20$, **or** other acceptable point \checkmark

time to next in phase condition = 38 (s) \checkmark

Allow "back in phase (for the first time)" as a valid explanation.

[**or** ($T = 1.90$ s so) $(n + 1) \times 1.90 = n \times 2.00$ \checkmark

gives $n = 19$ (oscillations of longer pendulum) \checkmark

minimum time between in phase condition = $19 \times 2.00 = 38$ (s) \checkmark]

3

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