M1.(a)
$$\frac{3.5}{(2\pi \times 0.088)} = 6.3 \text{ rev}$$

 $6.3 \times 2\pi$ = 39.8 rad or 40 rad \checkmark

If correct working shown with answer 40 rad give the mark Accept alternative route using equations of motion

1

(b) $\omega = v/r = 2.2/0.088 = 25 \text{ rad s}^{-1} \checkmark$

(C) (i) $E = \frac{1}{2} l \omega^2 + \frac{1}{2} m v^2 + mgh$ $= (0.5 \times 7.4 \times 25^{2})$ $+ (0.5 \times 85 \times 2.2^{2})$ $+(85 \times 9.81 \times 3.5)$ = 2310 🗸 + 206 1 + 2920 1 (= 5440 J or 5400 J) CE from 1b $\frac{1}{2}I\omega^{2} + \frac{1}{2}mv^{2} = 2310 + 210 = 2520 J$ $\frac{1}{2}$ I ω^2 + mgh = 2310 + 2920 = 5230 J $\frac{1}{2}mv^2 + mgh = 210 + 2920 = 3130 J$ Each of these is worth 2 marks

3

(ii) Work done against friction =
$$T\theta$$

= 5.2 × 40 = 210J \checkmark
Total work done = W = 5400 + 210
= 5600J \checkmark 2 sig fig \checkmark
CE if used their answer to i rather than 5400J
Accept 5700 J (using 5440 J)
Sig fig mark is an independent mark

3

(d) Time of travel = distance / average speed = 3.5 / 1.1 = 3.2s ✓

 $\frac{5600}{P_{ave}} = \frac{5600}{3.2} = 1750 \text{ W}$ $P_{max} = P_{ave} \times 2 = 3500 \text{ W} \checkmark$ OR accelerating torque = T = W/θ $= 5600 / 40 = 140 \text{ N m} \checkmark$ $P = T ω_{max} = 140 \times 25 = 3500 \text{ W} \checkmark$ CE from ii 1780 W if 5650 J used

M2.(a) (i) 8.3 rev =
$$8.3 \times 2^{\pi}$$
 rad \checkmark (= 52 rad)

Use of
$$\omega_{2}^{2} = \omega_{1}^{2} + 2\alpha\theta$$

 $0 = 6.4^{2} + 2 \times \alpha \times 52$ If eqtn(s) of motion used correctly with $\theta = 8.3$ (giving $\alpha = 2.5$), give 2 out of first 3 marks.

OR use of $\theta = \frac{1}{2}(\omega_1 + \omega_2)t$ leading to t = 16.25 s and $\omega_2 = \omega_2 + \alpha t$

α = (−) 0.39 ✓ rad s⁻² ✓ Accept: s⁻² Unit mark is an independent mark

1
4

1

2

2

[10]

(ii) $T = I\alpha$

= 8.2 × 10⁻³ × 0.39 = 3.2 × 10⁻³ N m ✓ *Give CE from a i*

(b) (i)
$$(W = T\theta \text{ or } W = T\omega t)$$
 where $\theta = 0.78 \times 270 \sqrt{(= 210 \text{ rad})}$

ratio =
$$\frac{900 \times 270}{0.67}$$
 or $\frac{2.4(3) \times 10^5}{0.67}$

(b) (ii) = 3.6×10^5 \checkmark

CE from b i. Must be in the form: number × 10^s with number

1

calculated correctly.

900 × 270 or 2.4(3) × 10^₅ or equivalent must be seen for 1stmark 1 mark for <u>only</u> writing 3.6 × 10^₅

2 (Total 9 marks)

M3. (a) (i)
$$T = Fr = 32 \times 0.15$$

= 4.8 N m \checkmark
(ii) $\omega = 2600 \times 2\pi/60 \ (= 270 \text{ rad s}^{-1}) \checkmark \text{ accept } 272 \text{ rad s}^{-1}$
total torque = 4.8 + 1.2 = 6.0 N m \checkmark
 $P = T\omega$
= 6.0 × 270 = 1620 W \checkmark

(b)
$$\alpha = \frac{270 - 0}{8.5} = 32 \text{ rad s}^{-2} \checkmark$$

 $I = T/\alpha = \frac{1.2}{32} = 0.038 \checkmark \text{ kg m}^2 \checkmark$
OR use of $\Theta = \frac{1}{2}(\omega_2 + \omega_1)\text{t} (= 1150 \text{ rad}) \checkmark$
and $\frac{1}{2}I \omega^2 = T\Theta$ leading to $I = 0.038 \checkmark \text{ kg m}^2 \checkmark$

3

(c)
$$E = \frac{1}{2}I \omega^2$$

= 0.5 × 0.038 × 270² = 1400 J \checkmark
 $P = E/t = 1400/0.005 = 280 \text{ kW} \checkmark$

[9]

2

M4. (a) (i)
$$T = Fr = 7.0 \times 0.075$$

= 0.53 (1) N m (1)

(ii)
$$P = T\omega$$

= 0.53 × 120 = 64 W (1)

(b) use of equation(s) of motion:

$$\theta = \frac{1}{2}(120 + 0) \times 6.2 = 370 \text{ rad}$$
 (1)

$$370/2\pi = 59 \text{ rotations (1)}$$

M5.(a) (i) two correct points from straight line (e.g. (0,0) and (300,150)) (1)

$$\alpha \left(= \frac{\omega_2 - \omega_1}{t} \right) = \frac{150 - 0}{0.3} = 500 \text{ rad s}^2 \text{ (1)}$$

(ii)
$$T (= I\alpha) = 4.20 \times 10^{-7} \times 500 = 2.1 \times 10^{-4} \text{ N m (1)}$$

(b) (i) resistive torque is negligible at low speeds (1) resistive torque increases as speed increases (1) resultant accelerating torque decreases so α decreases (1) until resistive torque = applied torque (1) zero net torque, so constant angular speed (1) (any three)

(ii) (use of $P = T\omega$ gives) $P = 2.1 \times 10^4 \times 225 = 4.73 \times 10^2$ W (1) (allow C.E. for value of *T*)

(iii) $E (= Pt) = 4.73 \times 10^2 \times 60 = 2.84 \text{ J}$ (1)

5

3

2

2

[5]